

# NAG C Library Function Document

## nag\_dormlq (f08akc)

### 1 Purpose

nag\_dormlq (f08akc) multiplies an arbitrary real matrix  $C$  by the real orthogonal matrix  $Q$  from an  $LQ$  factorization computed by nag\_dgelqf (f08ahc).

### 2 Specification

```
void nag_dormlq (Nag_OrderType order, Nag_SideType side, Nag_TransType trans,
    Integer m, Integer n, Integer k, const double a[], Integer pda,
    const double tau[], double c[], Integer pdc, NagError *fail)
```

### 3 Description

nag\_dormlq (f08akc) is intended to be used after a call to nag\_dgelqf (f08ahc), which performs an  $LQ$  factorization of a real matrix  $A$ . The orthogonal matrix  $Q$  is represented as a product of elementary reflectors.

This function may be used to form one of the matrix products

$$QC, Q^T C, CQ \text{ or } CQ^T,$$

overwriting the result on  $C$  (which may be any real rectangular matrix).

### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

### 5 Parameters

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order = Nag\_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

*Constraint:* **order = Nag\_RowMajor** or **Nag\_ColMajor**.

2: **side** – Nag\_SideType *Input*

*On entry:* indicates how  $Q$  or  $Q^T$  is to be applied to  $C$  as follows:

if **side = Nag\_LeftSide**,  $Q$  or  $Q^T$  is applied to  $C$  from the left;

if **side = Nag\_RightSide**,  $Q$  or  $Q^T$  is applied to  $C$  from the right.

*Constraint:* **side = Nag\_LeftSide** or **Nag\_RightSide**.

3: **trans** – Nag\_TransType *Input*

*On entry:* indicates whether  $Q$  or  $Q^T$  is to be applied to  $C$  as follows:

if **trans = Nag\_NoTrans**,  $Q$  is applied to  $C$ ;

if **trans = Nag\_Trans**,  $Q^T$  is applied to  $C$ .

*Constraint:* **trans = Nag\_NoTrans** or **Nag\_Trans**.

- 4: **m** – Integer *Input*  
*On entry:*  $m$ , the number of rows of the matrix  $C$ .  
*Constraint:*  $\mathbf{m} \geq 0$ .
- 5: **n** – Integer *Input*  
*On entry:*  $n$ , the number of columns of the matrix  $C$ .  
*Constraint:*  $\mathbf{n} \geq 0$ .
- 6: **k** – Integer *Input*  
*On entry:*  $k$ , the number of elementary reflectors whose product defines the matrix  $Q$ .  
*Constraints:*  
 if **side** = **Nag\_LeftSide**,  $\mathbf{m} \geq \mathbf{k} \geq 0$ ;  
 if **side** = **Nag\_RightSide**,  $\mathbf{n} \geq \mathbf{k} \geq 0$ .
- 7: **a**[*dim*] – double *Input/Output*  
**Note:** the dimension, *dim*, of the array **a** must be at least  
 $\max(1, \mathbf{pda} \times \mathbf{m})$  when **side** = **Nag\_LeftSide** and **order** = **Nag\_ColMajor**;  
 $\max(1, \mathbf{pda} \times \mathbf{k})$  when **side** = **Nag\_LeftSide** and **order** = **Nag\_RowMajor**;  
 $\max(1, \mathbf{pda} \times \mathbf{n})$  when **side** = **Nag\_RightSide** and **order** = **Nag\_ColMajor**;  
 $\max(1, \mathbf{pda} \times \mathbf{k})$  when **side** = **Nag\_RightSide** and **order** = **Nag\_RowMajor**.  
 If **order** = **Nag\_ColMajor**, the  $(i, j)$ th element of the matrix  $A$  is stored in **a**[(*j* – 1)  $\times$  **pda** + *i* – 1] and if **order** = **Nag\_RowMajor**, the  $(i, j)$ th element of the matrix  $A$  is stored in **a**[(*i* – 1)  $\times$  **pda** + *j* – 1].  
*On entry:* details of the vectors which define the elementary reflectors, as returned by **nag\_dgelqf** (f08ahc).  
*On exit:* used as internal workspace prior to being restored and hence is unchanged.
- 8: **pda** – Integer *Input*  
*On entry:* the stride separating matrix row or column elements (depending on the value of **order**) in the array **a**.  
*Constraints:*  
 if **order** = **Nag\_ColMajor**, **pda**  $\geq \max(1, \mathbf{k})$ ;  
 if **order** = **Nag\_RowMajor**,  
 if **side** = **Nag\_LeftSide**, **pda**  $\geq \max(1, \mathbf{m})$ ;  
 if **side** = **Nag\_RightSide**, **pda**  $\geq \max(1, \mathbf{n})$ .
- 9: **tau**[*dim*] – const double *Input*  
**Note:** the dimension, *dim*, of the array **tau** must be at least  $\max(1, \mathbf{k})$ .  
*On entry:* further details of the elementary reflectors, as returned by **nag\_dgelqf** (f08ahc).
- 10: **c**[*dim*] – double *Input/Output*  
**Note:** the dimension, *dim*, of the array **c** must be at least  $\max(1, \mathbf{pdc} \times \mathbf{n})$  when **order** = **Nag\_ColMajor** and at least  $\max(1, \mathbf{pdc} \times \mathbf{m})$  when **order** = **Nag\_RowMajor**.  
 If **order** = **Nag\_ColMajor**, the  $(i, j)$ th element of the matrix  $C$  is stored in **c**[(*j* – 1)  $\times$  **pdc** + *i* – 1] and if **order** = **Nag\_RowMajor**, the  $(i, j)$ th element of the matrix  $C$  is stored in **c**[(*i* – 1)  $\times$  **pdc** + *j* – 1].  
*On entry:* the  $m$  by  $n$  matrix  $C$ .  
*On exit:* **c** is overwritten by  $QC$  or  $Q^T C$  or  $CQ$  or  $CQ^T$  as specified by **side** and **trans**.

11: **pdc** – Integer*Input*

On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **c**.

*Constraints:*

if **order** = **Nag\_ColMajor**, **pdc**  $\geq \max(1, m)$ ;  
 if **order** = **Nag\_RowMajor**, **pdc**  $\geq \max(1, n)$ .

12: **fail** – **NagError** \**Output*

The NAG error parameter (see the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_INT

On entry, **m** =  $\langle value \rangle$ .

Constraint: **m**  $\geq 0$ .

On entry, **n** =  $\langle value \rangle$ .

Constraint: **n**  $\geq 0$ .

On entry, **pda** =  $\langle value \rangle$ .

Constraint: **pda**  $> 0$ .

On entry, **pdc** =  $\langle value \rangle$ .

Constraint: **pdc**  $> 0$ .

### NE\_INT\_2

On entry, **pda** =  $\langle value \rangle$ , **k** =  $\langle value \rangle$ .

Constraint: **pda**  $\geq \max(1, k)$ .

On entry, **pdc** =  $\langle value \rangle$ , **m** =  $\langle value \rangle$ .

Constraint: **pdc**  $\geq \max(1, m)$ .

On entry, **pdc** =  $\langle value \rangle$ , **n** =  $\langle value \rangle$ .

Constraint: **pdc**  $\geq \max(1, n)$ .

### NE\_ENUM\_INT\_3

On entry, **side** =  $\langle value \rangle$ , **m** =  $\langle value \rangle$ , **n** =  $\langle value \rangle$ , **k** =  $\langle value \rangle$ .

Constraint: if **side** = **Nag\_LeftSide**, **m**  $\geq k \geq 0$ ;

if **side** = **Nag\_RightSide**, **n**  $\geq k \geq 0$ .

On entry, **side** =  $\langle value \rangle$ , **m** =  $\langle value \rangle$ , **n** =  $\langle value \rangle$ , **pda** =  $\langle value \rangle$ .

Constraint: if **side** = **Nag\_LeftSide**, **pda**  $\geq \max(1, m)$ ;

if **side** = **Nag\_RightSide**, **pda**  $\geq \max(1, n)$ .

### NE\_ALLOC\_FAIL

Memory allocation failed.

### NE\_BAD\_PARAM

On entry, parameter  $\langle value \rangle$  had an illegal value.

### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

## 7 Accuracy

The computed result differs from the exact result by a matrix  $E$  such that

$$\|E\|_2 = O(\epsilon)\|C\|_2,$$

where  $\epsilon$  is the *machine precision*.

## 8 Further Comments

The total number of floating-point operations is approximately  $2nk(2m - k)$  if `side = Nag_LeftSide` and  $2mk(2n - k)$  if `side = Nag_RightSide`.

The complex analogue of this function is `nag_zunmlq` (f08axc).

## 9 Example

See Section 9 of the document for `nag_dgelqf` (f08ahc).

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